

CV3000 series Multismotor Multi-Spring Type Diaphragm Motors

Model HA2 to 4

OVERVIEW

The Multismotor is a pneumatic actuator of multi-spring type structure. It accepts the pneumatic output of positioners or other control equipments, converts the pneumatic force into a mechanical force with the diaphragm, and let the diaphragm force balanced with the spring force, there by setting the valve position. The Multismotor, which employ multiple springs and a high air supply pressure, are much more compact and light as compared with conventional actuators.

SPECIFICATIONS

Туре

Spring type piston cylinder

Action

Reverse acting

Туре

Action		Model	
Direct	HA2D	HA3D	HA4D
Reverse	HA2R	HA3R	HA4R

1) Direct action

As the air pressure fed to the top chamber of the diaphragm case increases, the actuator stem moves downward.

2) Reverse action

As the air pressure fed to the bottom chamber of the diaphragm case increases, the actuator stem moves upward.

Material

- Diaphragm case SS400
- Diaphragm
- Cloth embedded ethylene propylene rubber
- Actuator stem SUS304 stainless steel
- Yoke

FC200 (Optional: SCPH2)

Spring range

 $\begin{array}{l} 20 \text{ to } 98 \text{ kPa } \{0.2 \text{ to } 1.0 \text{ kgf/cm}^2\} \\ 80 \text{ to } 240 \text{ kPa } \{0.8 \text{ to } 2.4 \text{ kgf/cm}^2\} \end{array}$



Supply pressure

140 to 390 kPa {1.4 to 4.0 kgf/cm²}

Air connection

Rc 1/4 or 1/4NPT internal thread

Ambient temperature

-30 to 70°C

Optional accessories

Positioner*, pressure regulator with filter, hand wheel*, limit switch, solenoid valve, motion transmitter, booster relay, lock-up valve, and others.

- *Note)1)* For the optional items, refer to the specification sheets and installation drawing of respective accessories.
 - 2) Accessories with the asterisk mark (*) are selected from the following types depending on the actuators to be combined.

Actuator	Posit	ioner	Hand wheel		
	P/P	I/P	Тор	Side	
HA2 to 4	HTP	AVP/HEP	THM	SHM	

Dimensions and weight

Finish

ors.

Refer to Figure 1 to 3 and Table 2 to 4.

Blue (Munsell 10B5/10), or silver, or other specified col-

Performance

Output

Varies depending on utilized spring range and air supply pressue.

Accuracy

Table 1 Hysteresis error and linearity

Item	Sprii	ng range	20 to 98kPa {0.2 t o1.0 kgf/cm2}	80 to 240kPa {0.8 to 2.4 kgf/cm2}
Hysteresis	Without pos	itioner	3	-
error	With posit	ioner	1	1
Linearity	Without pos	itioner	±5	-
	With	HTP	±1	±1
	positioner	AVP/ HEP	±1	±1

Note) When no positioner is provided, performance varies by the type pf packing used.

DIMENSIONS

Table 2 Dimensions and weight of Multismotors

	0		Dimensions (mm)						Nominal	Maximum	
Model No.	Stroke (mm)	L	Н	ϕ d	t	К	φ Β	В	diaphragm area (cm ²)	chamber capacity (cm ³)	Weight (kg)
	14.3	121									
		103	334	56	22	$M9 \times 1$				1100	15
HA2D HA2R	HA2D HA2R 25.0						267	281	310		
		142									
	38.0	102	354	65	26	M12 × 1.25				1500	16
	25.0	144									
	25.0	113	407	65	26	M12 × 1.25				2800	31
HA3D HA3R	38.0	144					350	363	550		
max		102									
	55.0	130	459	80	30	M15 × 1.5				3400	32
		214									
	38.0	172									
HA4D	50.0	226	612	90	35	$M18 \times 1.5$	470	520	950	10000	68
HA4R	50.0	172	012			M18 × 1.5	4/0	520	930	10000	08
	75.0	251									



Figure 1Dimensions of Multismotor

Note) 1) Dimension L is as with air pressure $0 \text{ kPa} (\text{kgf/cm}^2)$.

2) The model numbers and L dimensions are listed with those of the direct action in the top row and those of the reverse action in the bottom row.

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φD

Model	Stroke			Dime	nsions	(mm)			Max. operating	Weight	
No.	(mm)	Α	$\phi \mathbf{B}$	В	С	<i>φ</i> D	Н	S	at hand wheel (N[kgf])	(kg)	фВ
	14.3				37	•	224		140	25	
HA2D HA2R	25.0	289	267	281	57	280 (200)	334	287	(190)	23	
	38.0				57	(===)	354		([19])	26	
	25.0				16		407			40	
HA3D HA3R	38.0	347	350	363	40	355	407	345	280 [29]	49	
	50.0				98		459		[]	50	
	38.0								150		
HA4D HA4R	50.0	476	470	520	114	570	612	474	450 [46.0]	120	< <u> </u>
	75.0								[]		

Table 3 Multismotor with side-mounted hand wheel

Note) 1) Dimension B is as shown in Figure 1.

 Dimension D is as shown in Figure 1.
Figures in parenthesis in ". D dimensions" and "maximum operating force required at hand wheel" colomns show for general bonnet of HLS single seated-control valve, when No.3 or No.4 disignated to SS2-8113-0200 is selected for pipe installation position. If valve and pipe sizes are for mounting with reducer, seslect pipe installation position of No.1, No.2, or top-hand wheel. Figure 2 Dimensions of Multismotor with side-mounted hand wheel

Table 4	Multismotor	with	top-mounted han	d wheel
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Model No	Stroke	Di	imensio	ons (mi	Max. operating	Weight	
Niouei Ivo.	(mm)	$\phi \mathbf{B}$	В	<i>\overline{\mathbf{D}}</i>	Н	hand wheel (N[kgf])	(kg)
	14.3				D:575		23
HA2D HA2R	25.0	267	281	200	R:558	140	23
	38.0				D:595 R:591	[14]	24
	25.0	350	363	355	D:694		16
HA3D HA3R	38.0				R:682	250 [26]	40
mon	50.0				98	[]	47
	38.0					10.0	
HA4D Ha4r	50.0	470	520	570	1010	400 [41]	110
	75.0					[]	



Figure 3 Dimensions of Multismotor with top-mounted hand wheel



Figure 4 Dimensios of actuator with positioner

Table 5

	P/P positioner		I/P positioner									
Model No.	НТР	HEP	AVP300 (KZ03 mounted on positioner)	AVP300 (KZ03 with bracket for separated mount)	AVP700 (KZ03 mounted on positioner)	AVP700 (KZ03 with bracket for separated mount)						
HA2	215	280	293	202	307	230						
HA3	245	310	323	232	337	260						
HA4	265	345	358	267	372	295						

Note) This dimensions are refference value.

Ordering Information

When ordering, please specify;

1) Model Number: HA2 to 4

2) Spring range

3) Stroke

4) Optional accessories

Please, read 'Terms and Conditions' from following URL before the order and use. http://www.azbil.com/products/bi/order.html

Specifications are subject to change without notice.

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