CP-PC-2263E



General-Purpose Self-Contained Photoelectric Sensors HP7 series

Nothing escapes his notice, no matter what the conditions.

Suitable for a variety of applications and conditions.

- Wide range of configurations and specifications
- Improved resistance to interference (e.g., fluorescent lights)
- Threaded metal mounting holes for more reliable installation
- Different frequency thru-scan model for stress-free installation
- Inexpensive, to meet current market needs

(To be certified in June 2012)

• Auto Adjust button for situations where detection is difficult

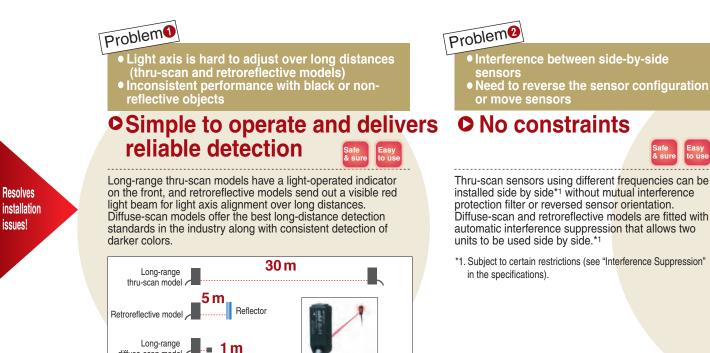
(To be certified in October 2012)

RoHs



CE

(VL)



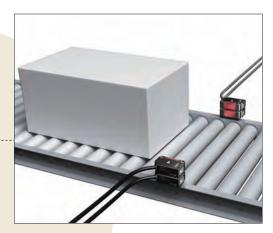
Light-operated indicator

diffuse-scan model /

▲Secure operating margin over a long distance

High-performance photoelectric sensors





▲ Installation of thru-scan sensors using different frequencies. Multiple units can operate side by side. As previously, two diffuse-scan or retroreflective sensors can be installed side by side.



Plastic screw holes aren't strong enough. Tightening the screws too hard or too quickly destroys the thread.

• Stronger mounting holes



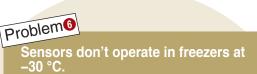
Threaded metal mounting holes provide improved mechanical strength.



suitable for a wide range of applications



▲ Thru-scan and diffuse-scan lenses made from oil-resistant modified polyallylate



Low temperature use OK



The widest operating temperature range available today—performance in freezer environments down to -30 °C is guaranteed.



▲ Operating temperature range is -30 to +55 °C *3. Low temperature code is available as an option.

Sensing range and type setup

First determine the optimum detection distance, light source, and sensing width, in order to minimize adjustment during installation.

Thru-scan models

Long range: 30 m

For long-distance applications or dust-filled environments such as multilevel parking garages and automated warehouses



Standard: 15 m

For standard thru-scan sensing applications

Short distance: 4 m

For applications requiring sensitivity adjustment at distances of up to 1 m

Retroreflective models*1

Standard: 5 m

The standard type offers the longest detection range in the industry

*1. Retroreflective sensors use polarizing filters to minimize sensing error due to light reflected off a high reflective surface.



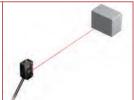
Diffuse-scan models

Infrared: 1 m

Infrared sensor with low susceptibility to color differences offering superior detection range in the industry

Red: 0.5 m

For near-distance applications requiring visual confirmation of the detected spot



Available soon Wide beam diffuse-scan models

Wide beam: 100 mm For applications detecting print circuit boards and inclined objects

Wide beam: 50 mm

For sensing print circuit boards while minimizing interference from surrounding areas.



Interference suppression

Using a combination of standard and different-frequency sensors (for thru scan), two sensors can be installed side by side without sacrificing space or distance.



Two thru-scan sensors (red and infrared)

The combination of a standard sensor and a different frequency sensor prevents interference without installing an mutual interference protection filter or reversing the orientation of one of the units. Effective for up to two units side by side.*²



Four thru-scan sensors (red)

Using an interference mutual protection filter, it is possible to install up to four units side by side*² without changing the orientation of any of the units.



Diffuse-scan sensor / retroreflective sensor

Automatic interference suppression allows two units to be installed in close proximity.*²

*2. Subject to certain restrictions (see "Interference Suppression" in the specifications)

Auto Adjust button

There are many situations where sensor systems can be installed using factory default settings. However in some situations, further adjustment will be required. Press the button on top of the unit to automatically adjust to the optimum sensitivity.

Auto Adjust

Auto Adjust

button

button

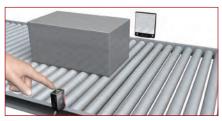
Thru-scan and retroreflective models

Inconsistent sensor operation when objects do not block the sensor beam properly



When used at factory settings, light passes through the object, affecting sensor performance.

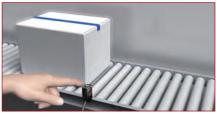
Sensor operation affected by background



Sensor is adjusted to appropriate sensitivity.



At the factory default setting, the sensor is constantly triggered by background.



Sensor is adjusted to appropriate sensitivity.

High-intensity red LED

Due to high-intensity four-element LED, light spot is easy to be recognized, helping to save time during light axis adjustment.



Excellent resistance to sunlight

Sensors are designed to provide a high level of resistance to sunlight (an industry-leading 40,000 lx).



How to use the Auto Adjust button

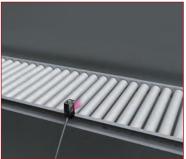
If sensor operation is not consistent at factory default settings, press the Auto Adjust button to adjust sensitivity automatically.

Tuning without a workpiece

In certain applications involving thru-scan and retroreflective sensors, the target may not block the sensor beam properly due to unwanted reflection and/or permeation of light. In some cases, diffuse-scan sensors may erroneously recognize background as the target. Tuning without a workpiece is the first step in trying to resolve the problem. Tuning without a workpiece refers to tuning with no target object present.

- Thru-scan and retroreflective sensors: Automatically adjusts sensitivity to trigger the sensor at approximately half the intensity of the light received when there is no target object present.
- Diffuse-scan sensor: Automatically adjusts sensitivity to trigger the sensor at approximately twice the intensity of the light received when there is no target object present.

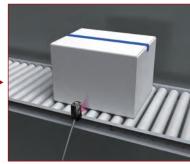
Sensor is triggered by background



Erroneously detects background as the target when operated at factory default settings (maximum sensitivity).



Tune without a workpiece. Background information is suppressed.



Cardboard boxes are now detected consistently and reliably.

Light seeps through semi-transparent target object



Light passes through semi-transparent target objects, affecting detection consistency.



Tune without a target object.



Target is now detected correctly. Note: Highly transparent objects cannot be detected. Check with actual target objects before running a machine.

Unwanted reflections affect detection consistency



Reflected light passes through gaps in the target object, causing detection errors.



Tune without a target object.

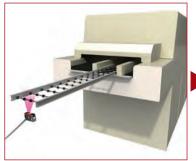


Palettes are now detected correctly.

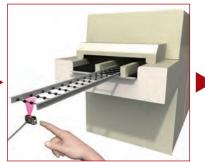
Two-point tuning

Two-point tuning is used in situations where tuning without a workpiece does not achieve the required results, or where it is necessary to detect target objects at a specific location. Sensitivity is automatically set to a value mid-way between the state when the target is present and when the target is absent.

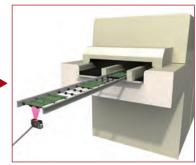
False detection



The sensor detects background objects such as the conveyor.



First, the sensor is exposed to the no-target state.



Next, the sensor is exposed to the state with a target present. The sensor is now able to distinguish between the two states.

Detection in a specific position



The aim is to sense the target object as it reaches the designated position.



Position tuning is performed at the required position.



The sensor operates around at this position. Note that the sensing distance can vary by as much as 15% from the set distance.

Catalog listings

| Detection method / Configulation | Detection range & light source | Catalog listing | Out put | Wiring method | |
|----------------------------------|--------------------------------|-----------------|---------|---------------|--|
| | 00mr /lisfering d | HP7-T41 | NPN | cable | 2m |
| | 30m/Infrared | HP7-T42 | PNP | cable | 2m |
| | 1 Star (De d | HP7-T11 | NPN | cable | Cable2mcable2m |
| Thru-scan | 15m/Red | HP7-T12 | PNP | cable | |
| | 15m/Infrared | HP7-T21 | NPN | N cable 2n | 2m |
| | 15m/mirared | HP7-T22 | PNP | cable | 2m 2m 2m 2m 2m 2m 2m 2m 2m 2m 2m 2m 2m 2 |
| | 4 | HP7-T51 | NPN | cable | 2m |
| | 4m/Red | HP7-T52 | PNP | cable | 2m |
| | 5m/Red | HP7-P11 | NPN | cable | 2m |
| Retroreflective | 5m/Red | HP7-P12 | PNP | cable | 2m |
| | 1m/Infrared | HP7-A43 | NPN | cable | 2m |
| Diffuse-scan | 1m/Infrared | HP7-A44 | PNP | cable | 2m |
| Jinuse-scan | 0.5m/Red | HP7-A13 | NPN | cable | 2m |
| · | 0.5m/Red | HP7-A14 | PNP | cable | 2m |
| | 100mm/Infrared | HP7-D23 | NPN | cable | 2m |
| Vide-beam diffuse scan | Toomm/minared | HP7-D24 | PNP | cable | 2m |
| Available soon | 50mm/Infrared | HP7-D63 | NPN | cable | 2m |
| | SUMMANEU | HP7-D64 | PNP | cable | 2m |

Thru-scan sensors different frequencies

| Combination model | Detection range & light source | Catalog listing | Out put | method | |
|-------------------|--------------------------------|-----------------|---------|--------|----|
| HP7-T41 type | 00m lafaan d | HP7-T45 | NPN | cable | 2m |
| HP7-T42 type | | HP7-T46 | PNP | cable | 2m |
| HP7-T11 type | 15m Ded | HP7-T15 | NPN | cable | 2m |
| HP7-T12 type | 15m Red | HP7-T16 | PNP | cable | 2m |
| HP7-T21 type | 15m Infrared | HP7-T25 | NPN | cable | 2m |
| HP7-T22 type | ISII IIIIared | HP7-T26 | PNP | cable | 2m |
| HP7-T51 type | - 4m Red | HP7-T55 | NPN | cable | 2m |
| HP7-T52 type | 411 Rea | HP7-T56 | PNP | cable | 2m |

Connection options

| | | Catalog listing | HP7-P11-L050 | HP7-P11-C003 | HP7-P11-S003 | HP7-P11-T |
|------------------------------------|--------------------------------|----------------------|---------------------------|--|-----------------------------|------------------------|
| Туре | ConfigurationBase model number | Connection type | 5 m cable | M12 preleaded ^{*2} connector | Quick Lock ^{*1 *2} | M8 connector |
| | number | Base model number | Base model number-L050 | Base model number-C003 | Base model number-S003 | Base model number-T |
| | 30m Infrared | HP7-T41 | ✓ | 1 | - | - |
| | Sommared | HP7-T42 | 1 | 1 | - | - |
| | 15m Red | HP7-T11 | O | O | 1 | 1 |
| Thru-scan | 15111 Neu | HP7-T12 | O | 1 | 1 | ✓ |
| Thru-scan | 15m Infrared | HP7-T21 | ✓ | - | - | - |
| | | HP7-T22 | 1 | - | - | - |
| | 4m Red | HP7-T51 | ✓ | 1 | - | - |
| | | HP7-T52 | 1 | 1 | - | - |
| Retroreflective | 5m Red | HP7-P11 | 0 | 0 | 1 | 1 |
| Reforenective | | HP7-P12 | 1 | 1 | 1 | 1 |
| | 1m Infrared | HP7-A43 | 1 | 1 | 1 | 1 |
| D:" | | HP7-A44 | ✓ | 1 | 1 | 1 |
| Diffuse-scan | 0.5m Red | HP7-A13 | 1 | 1 | 1 | 1 |
| | | HP7-A14 | ✓ | 1 | 1 | 1 |
| | 30 m Infrared sensors, | HP7-T45 | 1 | - | - | - |
| | different frequencies | HP7-T46 | ✓ | - | - | - |
| Thru coop | 15 m Red sensors, | HP7-T15 | 1 | 1 | 1 | 1 |
| Thru-scan sensors, different | different frequencies | HP7-T16 | ✓ | 1 | 1 | 1 |
| | 15 m Infrared sensors, | HP7-T25 | 1 | - | - | - |
| frequencies | different frequencies | HP7-T26 | ✓ | - | - | - |
| | 4 m Red sensors, | HP7-T55 | 1 | - | - | - |
| | different frequencies | HP7-T56 | √ | - | - | - |
| | 1 | | | 1 | 1 | 1 |

| Accessories Name | Configuration | Description | Catalog listing | Compatible model |
|--|---------------|---|---|------------------|
| | | Reflector size 47 x 47 mm | FE-RR22 (Scanning distance 0.05 to 5 m) | HP7-P_ |
| - | | Reflector size 30.8 x 30.8 mm | FE-RR18 (Scanning distance 0.05 to 3.3 m) | HP7-P_ |
| Reflector for retroreflective | | Reflector size 37 x 56 mm | FE-RR21 Scanning distance: horiz. mounting 0.05 to 5 m, vertical mounting 0.05 to 4.8 m* ² | HP7-P_ |
| model | | Reflector size 47 x 47 mm | FE-RR8 (Scanning distance 0.05 to 5 m) | HP7-P_ |
| | | Reflector size 30.8 x 30.8 mm | FE-RR15 (Scanning distance 0.05 to 3.3 m) | HP7-P_ |
| - | | Reflector size 8.6 x 29.5 mm | FE-RR20 Scanning distance: horiz. mounting 0.05 to 1.8m, vertical mounting 0.05 to 1.3 m* ² | HP7-P_ |
| | | Bottom-mounting L-bracket | HP-B08 | All models |
| Standard bracket | | Bottom-mounting L-bracket | HP-B09 | All models |
| | | Rear-mounting L-bracket | HP-B10 | All models |
| Wraparound | J | Wraparound vertical mounting bracket | HP-B11 | All models |
| mounting bracket | | Wraparound horizontal mounting bracket | HP-B12 | All models |
| Slit for thru-scan | 1 | Vertical slit | HP-SV05 HP-SV10 HP-SV20 | HP7-T_ |
| model | + | Horizontal slit | HP-SH05 HP-SH10 HP-SH20 | HP7-T_ |
| Mutual interference protection filter for thru-scan model | | Mutual interference can be prevented by changing the polarizing direction of 2 adjacent emitter-receiver pairs | HP-U02 | HP7-T1_/T5_ |

*2 horiz. mounting

vertical mounting

1



Specification

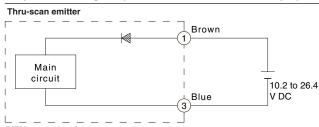
| Catalog | NPN | HP7-P11 | HP7-T51 | HP7-T11(Infrared) HP7-T21(Red) | HP7-T41 | HP7-A13 | HP7-A43 | |
|-------------------------|-------------|---|--|--|--|--------------------|-------------------|--|
| listing | PNP | HP7-P12 | HP7-T52 | HP7-T12(Infrared) HP7-T22(Red) | HP7-T42 | HP7-A14 | HP7-A44 | |
| Detection | method | Retroreflective*2 | | Thru-scan | | Diffuse | e-scan | |
| Power sup | oply | | | 10.2 to 26.4V DC (ripple 10% ma | ax.) | | | |
| Power co | nsumption | 14 mA max. | 22 mA max. | 25 mA max.(Infrared) 30 mA max.(Red) | 32 mA max. | 14 mA | 17 mA | |
| Scanning | distance | 5 m (with FE-RR8 reflector) | 4 m | 15 m | 30 m | 0.5 m | 1 m | |
| Target obj | | | | | Standard target o mm paper, 90 | | | |
| Differentia | l travel | - | | - | | 20% max. (at rated | scanning distance | |
| Operation | mode | | Light- | operate / Dark-operate selectable by o | peration button | | | |
| Output mo | ode*1 | | | NPN or PNP open collector | | | | |
| Control ou | utput | | | rrent: 100 mA (resistive load). Output c max. (at 100 mA switching current). 1. | | | | |
| Response | time | 1msec | 1 | 1 ms (different frequency model: 3 ms) | | 1m: | sec | |
| Light sou | | | Infrared (wavelength approx. 860 nm) | Red, 4 elements (wavelength approx. 645 nm) | Infrared (wavelength approx. 860 nm) | | | |
| Scanning | angle | 0.5 to 10° 2 to 20° - | | | | | | |
| Indicator | | Output ON: orange indicator ON at stable light and stable dark: green indicator Thru-scan emitter: power indicator 30 m thru-scan receiver: light-operated indicator on front | | | | | | |
| Ambient li immunity | ght | | HP7-T_, HP | escent lamp: 10,000 lux max. Sunlight: 77-P_: Minimum angle of incidence of s : Minimum angle of incidence of surrou | surrounding light = | 5° | | |
| Operating | temperature | | -3 | 30 to +55°C (without freezing or conder | nsation) *6 | | | |
| Operating | humidity | | 3 | 35 to 85% RH (without freezing or conc | lensation) | | | |
| Storage te | emperature | | | -40 to +70°C (without freezing or cond | ensation) | | | |
| Insulation | resistance | | | $20M\Omega$ min. (at 500Vdc) | | | | |
| Dielectric | strength | | 1,000Vac 50/ | 60Hz for one minute between electrica | lly live metal and c | ase | | |
| Vibration | resistance | | , | m peak-to-peak amplitude, 2 hours ea | , , | rections | | |
| Shock res | istance | | | 500m/s^2 10 times each in X, Y and Z d | irections | | | |
| | adjustment | | | Operation button | | | | |
| Protective | structure | IP67 (IEC standard) | | | | | | |
| Wiring me | thod | HP7: preleaded 2 m , | HP7L050 prelea | aded 5 m , HP7C003: M12 preleade | d connector 30 cm | , HP7T : M8 prele | eaded connector | |
| Circuit pro | otection | | E | Error prevention circuit at power on (ma Full wiring error protection | ax. 60 ms) | | | |
| Interferen suppressi | | Up to two diffuse-scan and retroreflective sensors, or two thru-scan sensors when operating at different frequencies or using mutu interference protection filters*4 (red), or up to four thru-scan sensors when using different frequencies together with mutual interference protection filters (red) | | | | | | |

And the restorted objects and objects that interfere with polarization.
 Retroreflective sensors feature polarizing filters; however, performance may be affected by highly reflective objects and objects that interfere with polarization.
 Response time may be longer if affected by light from other sensors.
 Mutual interference protection filters are for red light source.
 Interference suppression used in combination with different frequencies on thru-scan sensors is effective under the following conditions. Avoid head-on detection with close

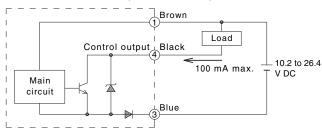
| CO | contacted mounting of diffuse-scan sensors. | | | | | | | |
|----|--|------------|-----------------|-----------|------------------|--|--|--|
| | Catalog listing | HP7-T5_ | HP7-T1_/HP7-T2_ | HP7-T4_ | HP7-T1_ + HP-U02 | | | |
| _ | Set distance | 1.3 m max. | 5 m max. | 10 m max. | 2 m max. | | | |
| | Sensitivity setting Maximum sensitivity (with light axis adjustment) | | | | | | | |

*6. Standard cord might get hardened under 0°C. Low temperature cord is available as an option.

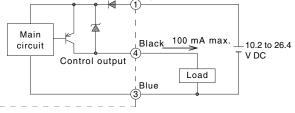
Output circuit diagram (Note that a FET is used for output)



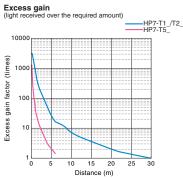
(NPN output type) Polarized retroreflector model, Thru-scan receiver, Diffuse-scan mode

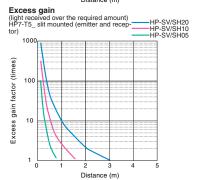


(PNP output type) Polarized retroreflector model, Thru-scan receiver, Diffuse-scan model Brown 1

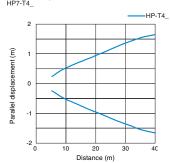


Thru-scan models (HP7-T1_/T2_/T5_)

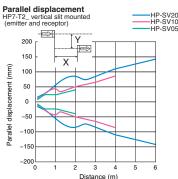


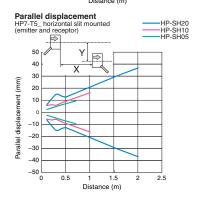


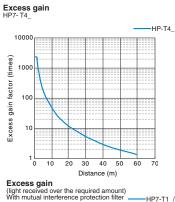
Parallel displacement HP7-T4_

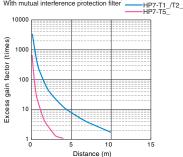


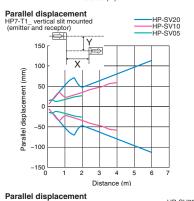


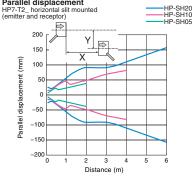




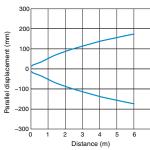


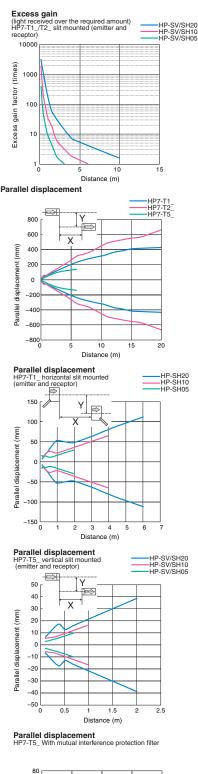


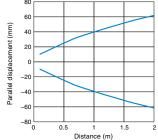






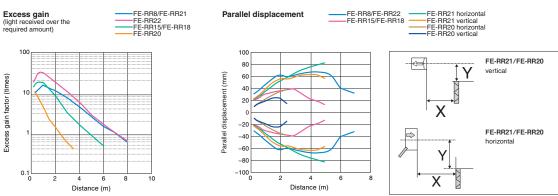




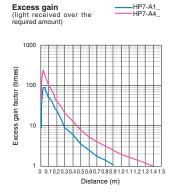


""The above summary of key characteristics should not be construed as a performance guarantee. Always test first under actual conditions and allow leeway as appropriate.

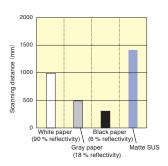
Retroreflective models (HP7-P1_)



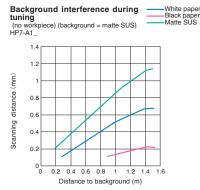
Diffuse-scan models(HP7-A1_/A4_)

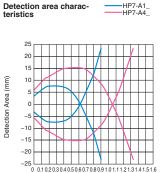






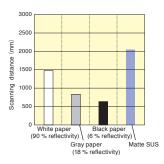
When used with highly reflective backgrounds, tilting the sensor may improve background suppression.



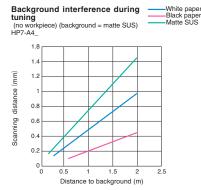


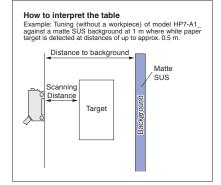
Distance (m)

Target specifications HP7-A4_



When used with highly reflective backgrounds, tilting the sensor may improve background suppression.

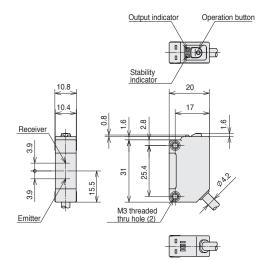




* All graphs represent typical data but not warranted specification. Use the sensor with appropriate margin.

External Dimensions (Unit: mm)

Retroreflective/Diffuse-scan

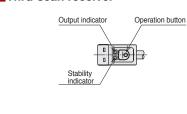


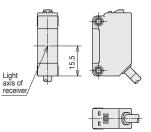
Thru-scan emitter

15.5

Light axis of emitter

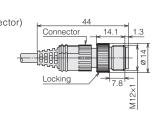
Thru-scan receiver



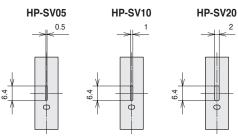


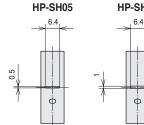
Connector part

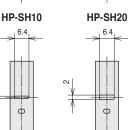
HP7-__-C_ (M12 preleaded connector)











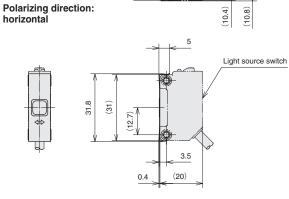
2

Filter

Polarizing direction: vertical







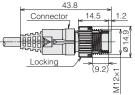
10.2

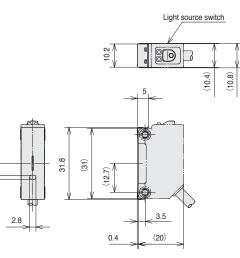


5.2

ø

Power supply indicator



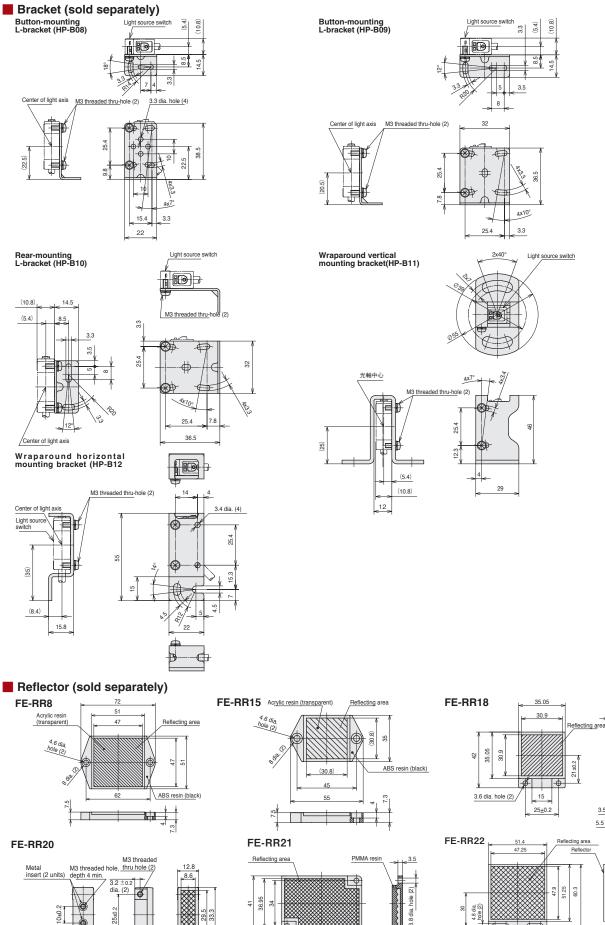


Scanning distance with slit on thru-scan model

| | | Catalog listing of a model used w | | |
|------------|---------|-----------------------------------|-------------------|--|
| | | HP7-T1_ HP7-T2_ | HP7-T5_ | |
| Slit width | Туре | Scanning distance | Scanning distance | |
| 0.5×6.4mm | HP-S_05 | 1.2m | 0.4m | |
| 1.0×6.4mm | HP-S_10 | 3m | 0.7m | |
| 2.0×6.4mm | HP-S_20 | 5m | 1.5m | |

Scanning distance when mutual interference protection filter is mounted on thru-scan model

| | Catalog listing of a model used with | | | | |
|------------------|--------------------------------------|------|--|--|--|
| Catalog listings | HP7-T1_ HP7-T5_ | | | | |
| HP-U02 | 7m | 1.8m | | | |



0.2(2)

3.5

5.5

3.4

PMMA

7.8

56

resin(white)

20.7

40

8.5±0.5





¢

PMMA

11 resin Reflecting area

Black ABS

re<u>sin</u>

Warning

• Designed for general industrial use, not for safety equipment.

• Do not connect this device to AC power. Doing so might cause rupture or burnout.

Handling precautions

- Tighten the mounting screws to a maximum torque of 0.8 N·m.
- Output is disabled upon power-up for 60ms max. until the unit stabilizes.
- For outdoor use, put inside a case, etc., to prevent direct exposure to sunlight and rain water.
- Avoid locations with strong vibration or impact. They may cause optical axis misalignment.
- Shield the lens from water and oil. Water or oil on the lens can cause faulty operation.
- Do not expose to chemicals (organic solvents, acids, alkalis).
- Use a cover or change the mounting direction to ensure correct sensor operation if there is heavy interference from ambient light.
- When used in a very dusty environment, be sure to take countermeasures to keep dust away from the lens surface by using a sealed case or air purging.
- Even when oil-resistant cord is used, do not use in a location subject to continuous splashing by water or oil, or where the unit is immersed in liquid. Ensure that the end of the cord is not subject to splashing by water or oil.
- A bend in the cord immediately after it exits the device should have a radius of a least 30 mm. Also, avoid use in which the cord receives repeated bending stress.
- Do not pull the cord with excessive force (≥ 50 N). Cord disconnection can cause burnout.
- Photoelectric sensors are assembled with precision. Never strike with another object. Especially if the lens surface is scratched or cracked, sensor performance may decline. Handle with care.
- To clean the lens or reflector, wipe lightly with a soft, clean cloth or cloth moistened with water. Do not use an organic solvent such as alcohol, benzene, acetone, or thinner.
- When multiple photoelectric sensors are used close together, mutual interference may occur. After installation, check the operation carefully before use.
- Standard cord might get hardened under 0°C. Do not bend or apply shock / vibration under 0°C. Low temperature cord is available.
- Sensor might not reliably detect highly reflective objects or objects that disrupt polarization (ex.: object covered with transparent film). In such a case try the following countermeasures: Sample countermeasures
- Mount the sensor at an angle to the target object.
- Increase the distance between the sensor and the target object.
- Tune the sensor without a workpiece.

Wiring precautions

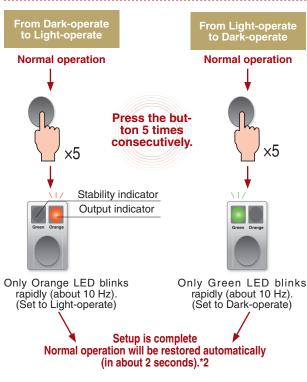
- If a cord extension is necessary, use wire at least 0.3 mm² in cross-sectional area and at most 100 m long.
- If the cord of photoelectric sensor are laid in the same conduit as high-voltage or power lines, inductance may cause malfunction or damage. Isolate the photoelectric sensor's cord or lay it in a separate conduit.
- When using a commercially available switching regulator, ground the frame ground and ground terminals. If used without grounding, switching noise may cause faulty operation.
- When using a load which generates an inrush current above the switching capacity, such as a capacitive load or incandescent lamp, connect a current-limiting resistor between the load and the output terminals. Otherwise, the output short-circuit protection function may be activated.

Adjustment method

- Thru-scan model and retroreflective model
 - 1. Move the emitter and receiver (main body and reflector in case of a retroreflective model) up, down, right, and left, and then align them in the center of the area where the green stable-operation indicator lights up.
 - Check sensor operation using a target object then use the Auto Adjust button to adjust the sensitivity setting.
- Diffuse-scan model
 - 1. Mount the photoelectric sensor pointing toward the desired detection position.
 - 2. Check sensor operation using a target object then use the Auto Adjust button to adjust the sensitivity setting.

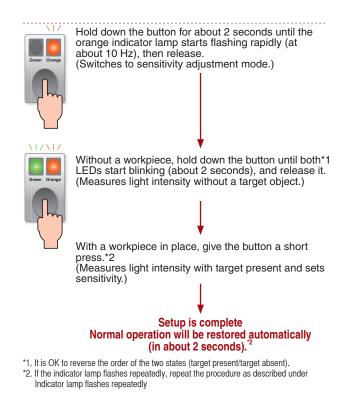
LO/DO Changeover

The operating mode is set to default at the factory, but can be changed as outlined below. Light-operate changes to Dark-operate, and Dark-operate changes to Light-operate.



2-point tuning

2-point tuning is used in situations when tuning without a workpiece does not provide a stable detection. Two-point tuning automatically sets the light sensitivity to a value mid-way between the state when the target is present and when the target is absent.



Tuning without a workpiece

The factory default setting is maximum sensitivity. If the target is not detected consistently at this setting, adjust the sensitivity using the Auto Adjust button as described below.

(1) Thru-scan models

If the target is translucent or has holes or openings that light can pass through, or if indirect sensor bean presents, the target object may not be able to block the sensor beam properly. By following the set up below, the sensitivity is automatically adjusted to trigger the sensor at approximately half the intensity of the light received when there is no target object present.

For thru-scan models, the light intensity may be too strong at the short distances noted below. This may cause the indicator lamp to flash repeatedly, as described under Indicator lamp flashes repeatedly.

HP7-T1___, HP7-T2___:1 m HP7-T5___:0.3 m

(2) Retroreflective models

If the target is translucent or has holes or openings that light can pass through, or if indirect sensor beam presents, the target object may not be able to block the sensor beam properly. By following the set up below, the sensitivity is automatically adjusted to trigger the sensor at approximately half the intensity of the light received when there is no target object present.

(3) Diffuse-scan models

Use Auto Adjust button in situations where reflection from background is too strong to detect a target. The sensitivity is automatically adjusted to trigger the sensor at approximately twice the intensity of the light received when there is no target object present.

X17



Hold down the button for about 2 seconds until the orange indicator lamp starts flashing rapidly (at about 10 Hz), then release. (Switches to sensitivity adjustment mode.)

Without a workpiece, give the button a short press. Both LEDs turn OFF. (Measures the light intensity without a target object and sets sensitivity as required.)

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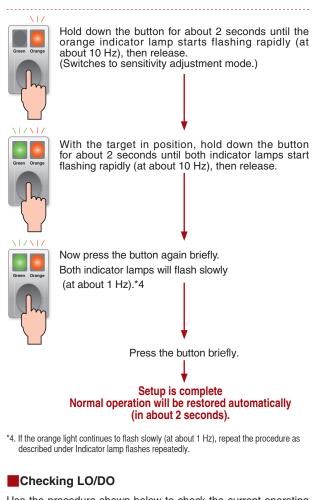
Setup is complete Normal operation will be restored automatically.*3 (in about 2 seconds).

*3. If the indicator lamp flashes repeatedly, repeat the procedure as described under Indicator lamp flashes repeatedly.

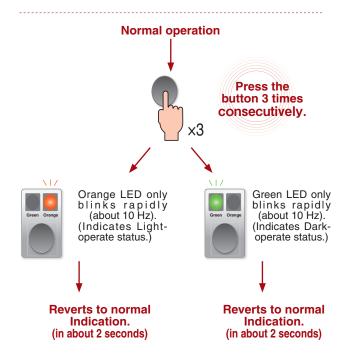
Position tuning

Position tuning is the procedure for configuring a diffuse-scan sensor to detect a target at a specific position. Position tuning has a maximum 15 % tolerance. Applicable distance range:

HP7-A1__:200–500 mm, HP7-A4__: 200–1,000 mm

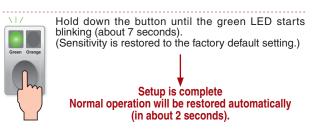


Use the procedure shown below to check the current operating mode.



When confused, or to restore the default setting (max. sensitivity)

The factory default setting is maximum sensitivity. This procedure is used to restore the factory default setting, which may be useful for resolving confusion during the setting procedure. This procedure will restore sensitivity to the factory default setting from any state (irrespective of how the indicator is flashing).



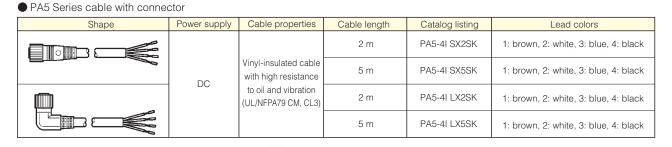
Indicator lamp flashes repeatedly

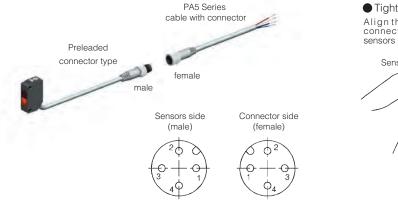
The table below lists the various states indicated by repeated flashing together with suggested responses. If the problem is not resolved, it may be necessary to try a different model of sensor.

| LED indicators | Status | Solution |
|--|--|---|
| Orange indicator flashes rapidly or both indicators flash | Tuning in prog- ress | Hold down the button until the green indicator flashes rapidly (about 7 seconds) to restore the factory default setting (maximum sensitivity). |
| rapidly (at about 10 Hz) | | |
| | Tuning Without a tuning workpiece Tuning failed - insufficient light | Thru-scan and retroreflective models Press the button once to revert to normal operation at the pre-tuning sensitivity. Adjust the light axis and then repeat the tuning procedure. |
| Crange LED only blinks slowly. (at about 1 Hz) | 2-point tuning Tuning failed - insufficient light at both points | Press the button once to revert to normal operation at the pre-tuning sensitivity. Thru-scan and retroreflective models Adjust the light axis and then re- peat the tuning procedure. Diffuse-scan models Move the sensor closer to the target to boost the reflected light intensity and then repeat the tuning procedure. |
| | 2-point tuning Tuning failed - too much light at both points | Thru-scan models Press the button once to revert to normal operation at the pre-tuning sensitivity. Reduce the amount of light by us- ing slits or tilting the optical axis, and then repeat the tuning proce- dure. |
| | Tuning without work- piece Setup is done but light intensity is too high. Stability Indicator may not light up. | Press the button once to revert to normal operation based on the tuning results. Use a workpiece to verify that the sensor works properly. Thru-scan models Reduce the amount of light by mounting slits or tilting the optical axis, and then repeat the tuning procedure. Diffuse-scan models Minimize the reflected light by painting the background black, and then repeat the tuning procedure. |
| Both LEDs blink slowly at the same time. (at about 1 Hz) | Tuning without work- piece Setup is done but too low. Stability Indicator may not light up. | Thru-scan and retroreflective models Press the button once to revert to normal operation based on the tun- ing results. Adjust the light axis and then repeat the tuning procedure. |
| | 2-point tuning Setup is done but Stability indicator may not light up(Not enough difference in light intensity between the two points). | Thru-scan, retroreflective, and diffuse-scan models Press the button once to revert to normal operation based on the tun- ing results. Check operation before use. |

PA5 Series cable

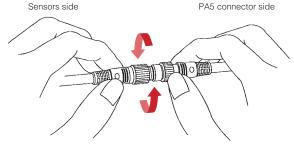
Be sure to use a PA5 Series cable with connector when connecting a preleaded connector or connector-type sensor.





Tightening the connector

Align the grooves and rotate the fastening nut on the PA5 connector by hand until it fits tightly with the connector on the sensors side.

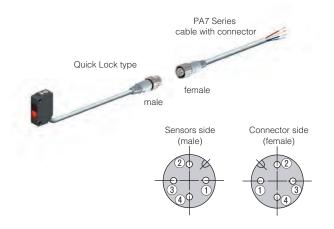


PA7 Series cable

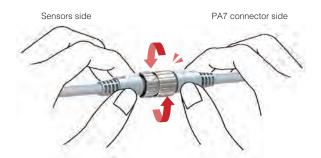
Be sure to use a PA7 Series cable with connector when connecting Quick Lock type sensor.

PA7 Series cable with connector

| Shape | Power supply | Cable properties | Cable length | Catalog listing | Lead colors |
|-------|--------------|---|--------------|-----------------|---------------------------------------|
| | 50 | Vinyl-insulated cable with high resistance | 2 m | PA7-4I SX2SK | 1: brown, 2: white, 3: blue, 4: black |
| | DC | to oil and vibration (UL/NFPA79 CM) | 5 m | PA7-4I SX5SK | 1: brown, 2: white, 3: blue, 4: black |

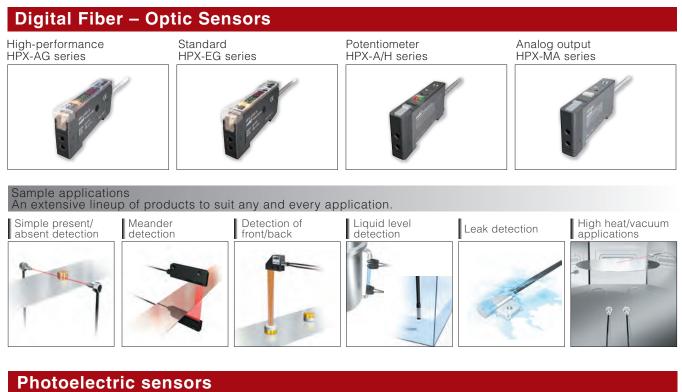


• Tightening the connector



Align the triangle mark and mate the male and female connector then rotate 45 degree to match the keys on the rings by hand.

Other products



Compact general-purpose photoelectric sensor HPJ





Designed for use machining applications

Compact proximity

sensors

Compact limit switches



Proximity sensors

General-purpose proximity sensor FL7M series





sensors APT series FL7N/M

Compact proximity

 φ 4/M5 mm

 φ 3/3.5 mm²

Square proximity sensor FL2 series



Mechanical switches

General-purpose limit switches





plunger configurations

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